

# Day 4 Editorial

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## A. Barcode

### Solution

- Dynamic programming
- Total complexity is  $O(n)$

## C. Capital

### Solution

- That's just a tree dynamic programming exercise

```
void goUp(int v, int parent, int maxUp) {
    int max1 = -1;
    int max2 = -1;
    up[v] = maxUp;
    for (int to : edges[v]) {
        if (to == parent) continue;
        if (max1 < 0 || down[max1] < down[to]) {
            max2 = max1;
            max1 = to;
        } else if (max2 < 0 || down[max2] < down[to]) {
            max2 = to;
        }
    }
    for (int to : edges[v]) {
        if (to == parent) continue;
        int maxDown = max1 == to ? max2 : max1;
        maxDown = maxDown >= 0 ? down[maxDown] : 0;
        goUp(to, v, Math.max(maxUp, maxDown));
    }
}
```

## Solution

- That's another tree dynamic programming exercise
- For every vertex compute  $\text{down}[v]$  — sum of distances going down in rooted tree
- And calculate  $\text{up}[v]$  — sum of distances that the one or more first edges on path going up

# E. $P = NP$

## Solution

- As you have to satisfy two of three
- Instead of  $x, y, z$  make
  - 1  $x \text{ OR } y$
  - 2  $x \text{ OR } z$
  - 3  $y \text{ OR } z$
- Solve 2SAT problem

## F. Connections

### Solution

- Problem is just equivalent to number of correct bracket sequences
- Answer is catalan sequence
- Calculate using dynamic programming

## G. Ivan's Game

### Solution

- Cost of the move  $(S_1 - K_1) \times (S_2 - K_2)$ 
  - Subtract 1 from all the values, so cost of the move is now  $S_1 \times S_2$
- There's no profit making moves  $K_1 > 1$  and  $K_2 > 1$ 
  - Sum of all pairs of numbers added
  - Can divide each sequence into two, will be better
- If  $K_1 = 1$  or  $K_2 = 1$  it's just sum of multiplications of a number from one of the sequences to some numbers of other sequences
  - The same as taking pairs of numbers one by one
- So do dynamic programming  $f[a][b]$  — the smallest sum can make if all numbers  $i > a$  in first sequence and  $j > b$  in second sequence are taken
- You either take both, or one of the numbers

## Solution

- State is (values of registers, instruction pointer). Total number of states is  $2^{32} \times 16$  which is too much.
- Not all registers are important
- If we have `jmp x` a command than a register is important
- If we have `MOV a b` command and a is important than b is also important
- Same rules for other instructions (one instruction add not more than one important register)
- Not more than 16 important registers
- Total number of interesting states is  $2^{16} \times 16$ . So we can do bfs on all interesting states.



# J. Packing Trees

## Solution

- The problem is to color tree into several colors, so that expected number of color changes on path from vertex to root is minimized
- First observation: every color makes connected set of vertices
  - If not, you can make a new color for one of the regions, answer won't change

# J. Packing Trees

## Solution

- You can calculate the expected number of times each edge is traversed
- Do the dynamic programming:  $f[v][B]$  — the expected number of color changes in subtree rooted at  $v$ , so that the number of vertices colored to the same color as root is  $B$
- For every of children you either start new color component, then you added number of times you traversed the edge
- Or continue the same color
- Do the internal DP:  $g[i][B]$  — the expected number of color changes in the first  $i$  children so that  $B$  vertices of the same color used

## Solution

- We need to solve a system of linear inequalities
- Common way of doing this is Simplex algorithm or Ellipsoid algorithm
- But this task also can be solved with approximate algorithms

## L. Robots on a Board

### Solution

- If robot repeats his list of commands  $2^{24}$  times, he will fall off the board
- So we need only  $2^{24} \times 256$  moves to make
  - This will exceed the time limit
- Robots can collide in next 256 moves only if the distance between them is not more than 256
- Let's precalculate for every of second robot's position respective to first robot ( $256 \times 256$  positions) will they collide and when
  - This is calculated just simulating for all the starting respective positions
- Then we can simulate robots' programs in  $O(1)$ 
  - Lookup will they collide in one iteration
  - If not change their position
  - Repeat  $2^{24}$  times

# M. Safe Cracking

## Solution

- That is the standard problem
- The optimal final position of all holes coincide with one of the initial positions
- $O(n^2)$  solution is just try all of them, for every other compute minimum of two distances and sum up
- To do  $O(n)$  you can use two-pointers technique, the elements form two segments in cyclic array, if you sort all the numbers initially
- Accurately implement

### Solution

- The problem says that given some polynomial values in calculated modulo some prime in some points, get the polynomial
- [https://en.wikipedia.org/wiki/Lagrange\\_polynomial](https://en.wikipedia.org/wiki/Lagrange_polynomial)
- You can divide modulo prime

## O. Stairs

### Solution

- The key idea is just when two guys meet, they keep moving not interfering with each other

## P. Protect the Statues

### Solution

- Problem is to find the area of convex hull of all circles
- Since we need only  $\frac{1}{10}$  accuracy and coordinates are up to  $10^4$
- Get 1000 points on each circle
- Build convex hull
- Output area of the polygon



## Q. Street Directions

### Solution

- Create two edges for every bridge in both directions
- Take biconnected component, use DFS to direct the edges:
  - Build spanning tree using DFS
  - The edges in spanning tree direct from it's parent to child
  - The other edges direct from descendants to ancestors

## R. Word Rings

### Solution

- Build graph:
  - $26^2$  vertices for all pairs of letters
  - Every word is an edge from its first two letters to its last two
- Problem is to find the minimum mean cost cycle
- Answer is:  $\min_v \max_i \frac{d_{n,v} - d_{i,v}}{n-i}$
- Where  $d_{i,v}$  — is the shortest path from some vertex  $s$  to  $v$  with  $i$  edges
- $s$  is the vertex that everything is reachable from it
- For more information find papers about minimum mean cost cycle